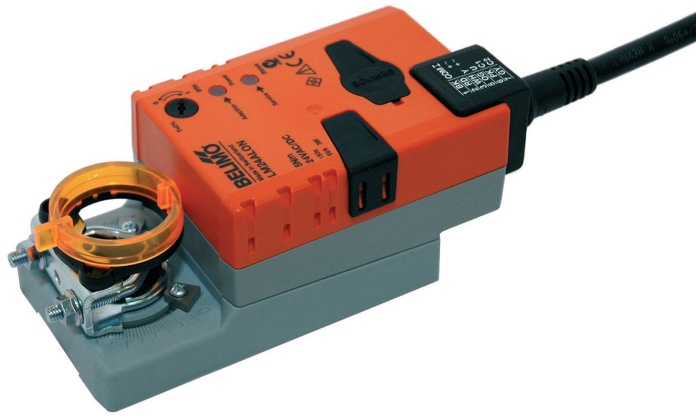


Communicative damper actuator for adjusting dampers in technical building installations

- Air damper size up to approx. 1 m²
- Nominal torque 5 Nm
- Nominal voltage AC/DC 24 V
- Communication via LONWORKS® (FTT-10A)
- Conversion of sensor signals
- Integrated temperature controller



LONMARK®

Technical data

Electrical data	Nominal voltage	AC/DC 24 V	
	Nominal voltage frequency	50/60 Hz	
	Nominal voltage range	AC 19.2...28.8 V / DC 21.6...28.8 V	
	Power consumption in operation	2.5 W	
	Power consumption in rest position	1.3 W	
	Power consumption for wire sizing	5 VA	
	Connection supply / control	Cable 1 m, 6 x 0.75 mm ²	
	Data bus communication	Certified	According to LONMARK® 3.3
Processor		Neuron 3150	
Transceiver		FTT-10A	
Functional Profile as per LONMARK®		Damper Actuator Object #8110 Open Loop Sensor Object #1 Thermostat Object #8060	
LNS plug-in for actuator / sensor / controller		Can be run with any LNS-based integration tool (Min. for LNS 3.x)	
Service button and status LED		According to LONMARK® guidelines	
Conductors, cables		Signal cable lengths, cable specifications and topology of the LONWORKS® network in accordance with the ECHELON® guidelines	
Functional data		Torque motor	Min. 5 Nm
		Torque variable	25%, 50%, 75% reduced
		Position feedback U	DC 2...10 V
	Position feedback U note	Max. 0.5 mA	
	Position feedback U variable	Start point DC 0.5...8 V End point DC 2.5...10 V	
	Position accuracy	±5%	
	Direction of motion motor	Selectable with switch 0 / 1	
	Direction of motion note	Y = 0 V: At switch position 0 (ccw rotation) / 1 (cw rotation)	
	Direction of motion variable	Electronically reversible	
	Manual override	Gear disengagement with push-button, can be locked	
	Angle of rotation	Max. 95°	
	Angle of rotation note	can be limited on both sides with adjustable mechanical end stops	
	Running time motor	150 s / 90°	
	Motor running time variable	35...150 s	
	Adaption setting range	manual	
	Adaption setting range variable	No action Adaption when switched on Adaption after pushing the gear disengagement button	
	Override control, controllable via nviManOvrd	MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position) = 50%	
	Sound power level motor	35 dB(A)	
	Spindle driver	Universal spindle clamp 6...20 mm	
	Position indication	Mechanically, pluggable	
Safety	Protection class IEC/EN	III Safety extra-low voltage	

Technical data

Safety	Protection class UL	UL Class 2 Supply
	Degree of protection IEC/EN	IP54
	Degree of protection NEMA/UL	NEMA 2, UL Enclosure Type 2
	EMC	CE according to 2004/108/EC
	Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14
	Certification UL	cULus according to UL 60730-1A, UL 60730-2-14 and CAN/CSA E60730-1:02
	Mode of operation	Type 1
	Rated impulse voltage supply / control	0.8 kV
	Control pollution degree	3
	Ambient temperature	-30...50 °C
	Non-operating temperature	-40...80 °C
	Ambient humidity	95% r.h., non-condensing
	Maintenance	Maintenance-free
	Weight	Weight approx.

Safety notes



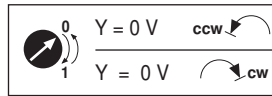
- The device must not be used outside the specified field of application, especially not in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea)water, snow, ice, insolation or aggressive gases interfere directly with the actuator and that is ensured that the ambient conditions remain at any time within the thresholds according to the data sheet.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section, the design, the installation site and the ventilation conditions must be observed.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

Product features

Mode of operation	The actuator is equipped with an integrated interface for LONWORKS®. The actuator can be directly connected to the LON network and controlled via the transceiver FTT-10A
Converter for sensors	Connection option for a sensor (passive or active sensor or switching contact). In this way, the analogue sensor signal can be easily digitised and passed along to LONWORKS®.
Integrated temperature controller	The device has an integrated temperature controller (Thermostat Object LONMARK® #8060). Other control variants upon request. The temperature controller can be set using the LNS Plug-In from Belimo.
Parameterisable actuators	The factory settings cover the most common applications. Single parameters can be modified with the Belimo Service Tools MFT-P or ZTH EU.
Simple direct mounting	Simple direct mounting on the damper spindle with an universal spindle clamp, supplied with an anti-rotation device to prevent the actuator from rotating.
Manual override	Manual override with push-button possible (the gear is disengaged for as long as the button is pressed or remains locked).
High functional reliability	The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.
Adjustable angle of rotation	Adjustable angle of rotation with mechanical end stops.

Product features

Home position The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out a synchronisation. The synchronisation is in the home position (0%).
The actuator then moves into the position defined by the positioning signal.



Adaption and synchronisation An adaption can be triggered manually by pressing the “Adaption” button or with the PC-Tool. Both mechanical end stops are detected during the adaption (entire setting range).
Automatic synchronisation after pressing the gearbox disengagement button is configured. The synchronisation is in the home position (0%).
The actuator then moves into the position defined by the positioning signal.
A range of settings can be adapted using the PC-Tool (see MFT-P documentation)

Accessories

	Description	Type
Electrical accessories	Auxiliary switch, add-on, 1 x SPDT	S1A
	Auxiliary switch, add-on, 2 x SPDT	S2A
	Auxiliary switch, add-on, 2 x SPDT, grey	S2A GR
	Feedback potentiometer 140 Ohm, add-on	P140A
	Feedback potentiometer 140 Ohm, add-on, grey	P140A GR
	Feedback potentiometer 200 Ohm, add-on	P200A
	Feedback potentiometer 500 Ohm, add-on	P500A
	Feedback potentiometer 500 Ohm, add-on, grey	P500A GR
	Feedback potentiometer 1 kOhm, add-on	P1000A
	Feedback potentiometer 2.8 kOhm, add-on	P2800A
	Feedback potentiometer 2.8 kOhm, add-on, grey	P2800A GR
	Feedback potentiometer 1 kOhm, add-on, grey	P1000A GR
	Feedback potentiometer 5 kOhm, add-on	P5000A
	Feedback potentiometer 5 kOhm, add-on, grey	P5000A GR
	Feedback potentiometer 10 kOhm, add-on	P10000A
	Feedback potentiometer 10 kOhm, add-on, grey	P10000A GR
	Connecting cable 5 m, A+B: RJ12 6/6, To ZTH/ZIP-USB-MP	ZK1-GEN
Connection cable 5 m, A: RJ11 6/4, B: Free wire end, To ZTH/ZIP-USB-MP	ZK2-GEN	
Mechanical accessories	Shaft extension 170 mm, for damper spindles Ø 6...20 mm	AV6-20
	Spindle clamp for LM..A, clamping range 6...20 mm	K-ELA
	Spindle clamp for LM..A, clamping range 6...10 mm	K-ELA10
	Spindle clamp for LM..A, clamping range 6...13 mm	K-ELA13
	Spindle clamp for LM..A, clamping range 6...16 mm	K-ELA16
	Universal mounting bracket 180 mm	Z-ARS180
	Form fit insert 10x10 mm, for LM..A	ZF10-LMA
	Form fit insert 12x12 mm, for LM..A	ZF12-LMA
	Form fit insert 8x8 mm, for LM..A	ZF8-LMA
	Form fit insert 10x10 mm, with angle of rotation limiter and position indication for LM..A	ZFRL10-LMA
	Form fit insert 12x12 mm, with angle of rotation limiter and position indication for LM..A	ZFRL12-LMA
	Form fit insert 8x8 mm, with angle of rotation limiter and position indication for LM..A	ZFRL8-LMA
	Position indication for LM..A, NM..A, SM..A, GM..A	Z-PI

Accessories

	Description	Type
Service Tools	Service Tool, for MF/MP/Modbus/LonWorks actuators and VAV-Controller	ZTH EU
	Belimo PC-Tool, software for adjustments and diagnostics	MFT-P
	Adapter to Service-Tool ZTH	MFT-C

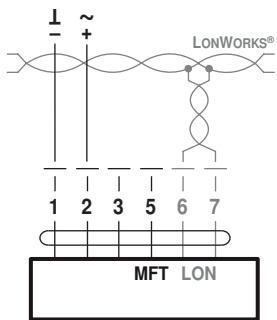
Electrical installation



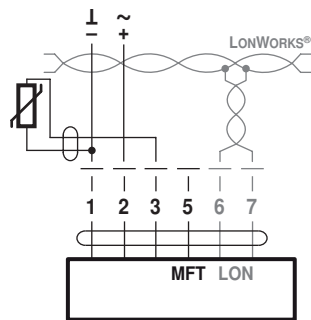
Notes • Connection via safety isolating transformer.

Wiring diagrams

Connection without sensor



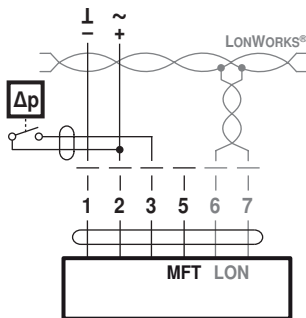
Connection with passive sensor, e.g. Pt1000, Ni1000, NTC



Ni1000	-28...+98°C	850...1600 Ω ²⁾
PT1000	-35...+155°C	850...1600 Ω ²⁾
NTC	-10...+160°C ¹⁾	200 Ω...60 kΩ ²⁾

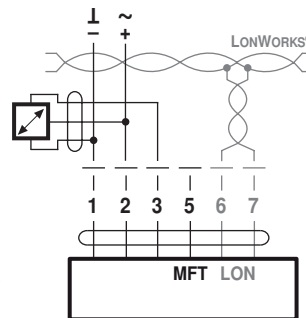
Sensor scaling:
The sensors can be scaled with the sensor plug-in (sensor table).
1) Depending on type
2) Resolution 1 Ohm

Connection with switching contact, e.g. Δp monitor



Switching contact requirements:
The switching contact must be able to switch a current of 16 mA at 24 V accurately.

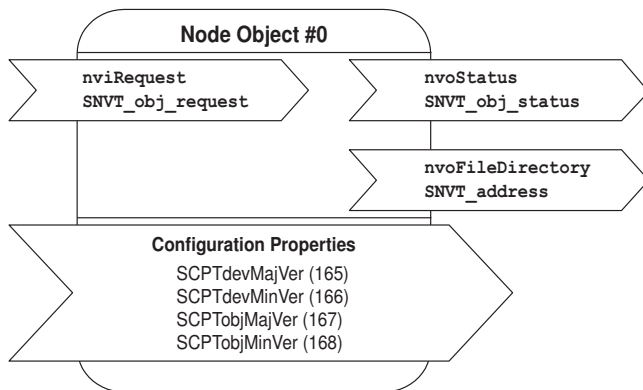
Connection with active sensor, e.g. 0...10 V @ 0...50°C



Possible voltage range:
0...32V (Resolution 30 mV)
Sensor scaling:
The sensors can be scaled with the sensor plug-in (sensor table)

Functional Profile as per LONMARK®

The LON-capable actuator is certified by LONMARK®. The following actuator functions are made available via the LONWORKS® network as standardised network variables in accordance with LONMARK®: the Node Object #0, the Damper Actuator Object #8110, the Open Loop Sensor Object #1 and the Thermostat Object #8060.



Node Object #0

The node object contains the object status and object request functions.

nviRequest: SNVT_obj_request

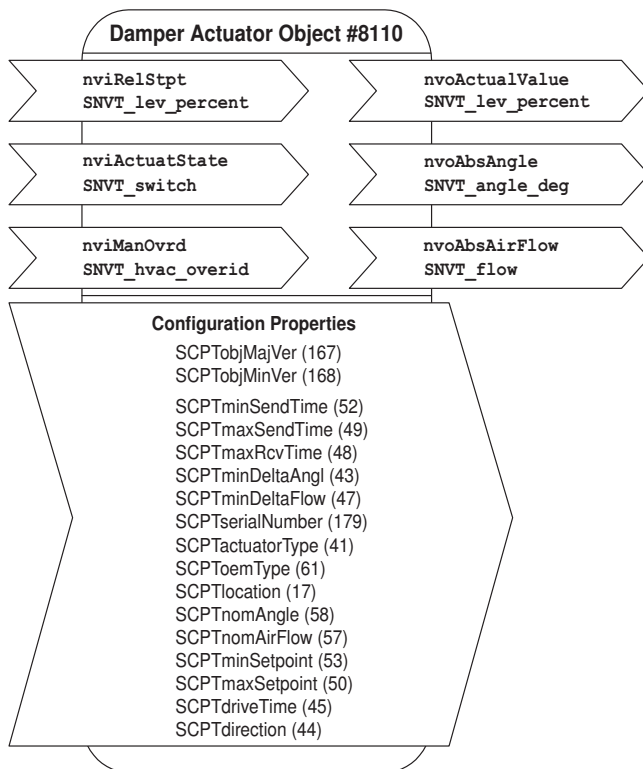
Input variable for requesting the status of a particular object in the node.

nvoStatus: SNVT_obj_status

Output variable that outputs the current status of a particular object in the node.

nvoFileDirectory: SNVT_address

Output variable that shows information in the address range of the Neuron chip.



Damper Actuator Object #8110

The actuator object is used to display the functions of the actuator on the page of the LONWORKS® network.

nviRelStpt: SNVT_lev_percent

Via this input variable, the setpoint in % for the actuator is specified (0...100% = Min...Max). This variable is normally linked to the output variable of an HVAC controller.

nviActuateState: SNVT_switch

A preset position is assigned to the actuator via this input variable. Note on priority: The variable which was most recently active, either nviActuatorState or nviRelStpt, has priority.

nviManOvr: SNVT_hvac_overid

see table «Override control with SNVT nviManOvr»

nvoActualValue: SNVT_lev_percent

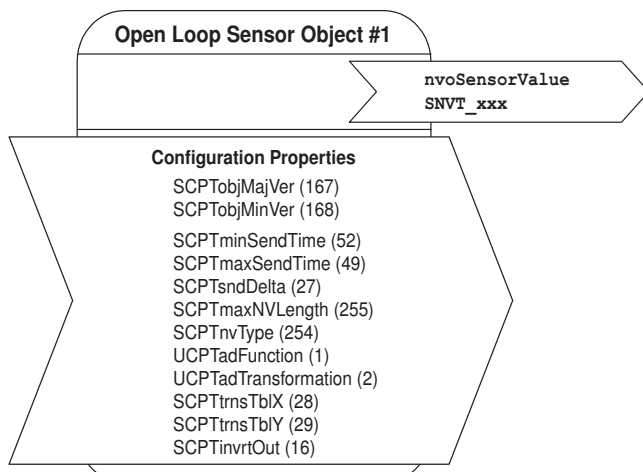
This output variable shows the current actual position of the actuator and can be used for control circuit feedback or for displaying positions.

nvoAbsAngle: SNVT_angle_deg

This output variable shows the current angle of rotation of the actuator and can be used to display the position or for service purposes.

nvoAbsAirFlow: SNVT_flow

This output variable is inactive with this actuator and shows a constant value of 65535 (this variable is only active in conjunction with LON-capable VAV controllers).



Open Loop Sensor Object #1

One sensor can be connected to the actuator.

A passive resistance sensor (e.g. Ni1000), an active sensor (output 0 ... 32 V) or a switch (On/Off) can be connected. In the case of the open loop sensor object, the measured sensor values are transferred to the LONWORKS® network.

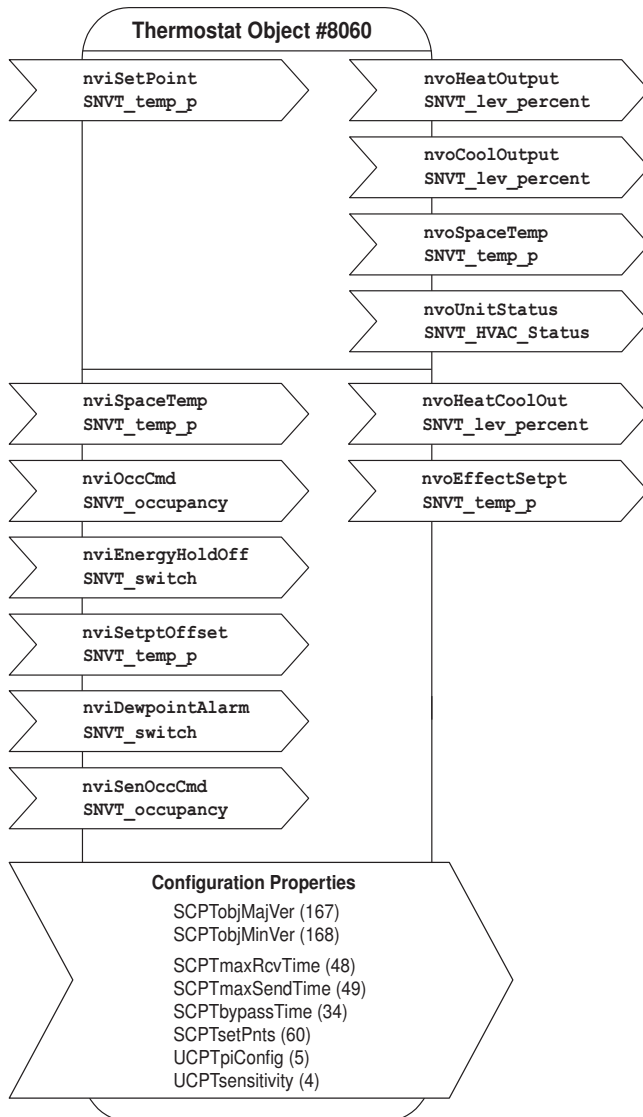
nvoSensorValue: SNVT_XXX

This output variable shows the current sensor value. Depending on the connected sensor, the output variable can be configured via the sensor plug-in and specifically adapted to the system.

The SNVT .. can be configured as:		
SNVT_temp_p	SNVT_lev_percent	SNVT_lux
SNVT_temp	SNVT_abs_humid	SNVT_press_p
SNVT_switch	SNVT_enthalpy	SNVT_smo_obscur
SNVT_flow	SNVT_ppm	SNVT_power
SNVT_flow_p	SNVT_rpm	SNVT_elec_kwh

Functional Profile as per LONMARK®

Individual room control solutions can be implemented with the thermostat object LONMARK® #8060. An LNS plug-in is available for configuring the controller parameters.



Thermostat Object #8060

nviSetPoint: SNVT_temp_p

Setpoint specification for the controller from the higher-level system or the room control unit. If this variable is not linked, then the local setpoints of the controller object apply (can be adjusted via plug-in).

The setpoint specification from the higher-level system influences the setting on the controller as follows:

Example: Comfort setpoint for heating = 21 °C and Comfort setpoint for cooling = 23 °C. The median point between heating and cooling is thus 22 °C. Now, if the external setpoint (nviSetPoint) is 23 °C, then the heating setpoint will shift to 22 °C and the cooling set point to 24 °C. The setpoints for Pre-Comfort heating and cooling will also be shifted accordingly.

nviSpaceTemp: SNVT_temp_p

Room temperature from external room sensor. It is imperative that this variable be linked; typically, it is linked with the variable of the sensor object.

nviOccCmd: SNVT_occupancy

Occupancy specification from the command centre (for the function, see the table entitled «Functions Inputs Occupancy» page 5).

nviEnergyHoldOff: SNVT_switch

In the case of active EnergyHoldOff, the controller will be set to the Building Protection setpoints.

nviSetPtOffset: SNVT_temp_p

Shifting of the room control unit. If the nviSetPoint is linked, then this input has an influence on the variable value of nviSetPoint, i.e. it corrects it. Otherwise, the Comfort and Pre-Comfort setpoints for heating and cooling will be adjusted directly by the amount of the shift (compare example with nviSetPoint).

nviDewpointAlarm: SNVT_switch

In the case of active DewpointAlarm, the controller will be set to the Building Protection setpoints. The cooling sequence is deactivated.

nviSenOccCmd: SNVT_occupancy

Occupancy specification from the local occupancy switch (for the function, see the table entitled «Functions Inputs Occupancy» page 5).

nvoHeatOutput: SNVT_lev_percent

Control signal for heating.

nvoCoolOutput: SNVT_lev_percent

Control signal for cooling.

nvoSpaceTemp: SNVT_temp_p

Displays the room temperature of the nviSpaceTemp. If nviSpaceTemp is not linked, then the variable will display the value 0x7FFF.

nvoUnitStatus: SNVT_HVAC_Status

Displays the operating mode of the controller (in accordance with Functional Profile #8060).

nvoHeatCoolOut: SNVT_lev_percent

Depicts the heating and cooling sequence for controlling the 6-way characterised control valves (see illustration, page 5).

This outlet runs parallel to the nvoCoolOutput or the nvoHeatOutput, respectively.

Cooling = 33 ... 0%

Valve closed 33 ... 66%

Heating = 66 ... 100%

nvoEffectSetpt: SNVT_temp_p

Shows the actual setpoint of the controller.

Note

A restart is necessary after accessing network variables for the purpose of rewriting them or after deleting links in order to initialise the variables.

Functional Profile as per LONMARK®

Functions Inputs Occupancy

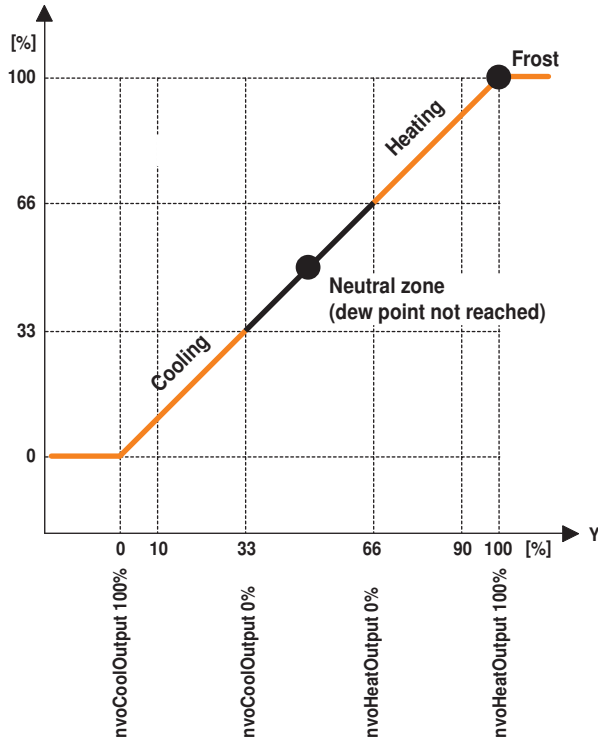
Occupancy specification from nviOccCmd command centre	Occupancy switch nviSenOccCmd	Room operating status	Comfort extension
OC_OCCUPIED	OC_OCCUPIED	Comfort	
	OC_UNOCCUPIED	Comfort	
	OC_NUL (default)	Comfort	
OC_STANDBY	OC_OCCUPIED	Bypass	Occupied time is extended by the amount of the bypass time (comfort time) (can be adjusted in the plug-in)
	OC_UNOCCUPIED	Pre-Comfort	
	OC_NUL (default)	Pre-Comfort	
OC_UNOCCUPIED	OC_OCCUPIED	Building Protection	
	OC_UNOCCUPIED	Building Protection	
	OC_NUL (default)	Building Protection	
OC_NUL (default)	OC_OCCUPIED	Comfort	
	OC_UNOCCUPIED	Pre-Comfort	
	OC_NUL (default)	Comfort	

Note

The function nviOccCmd has a higher priority than the function nviSenOccCmd.

Funktion nvoHeatCoolOut

nvoHeatCoolOut
SNVT_lev_percent



Typical application

Heating / cooling with Belimo 6-way characterised control valve.

Note chilled ceiling application

In the case of active DewPointAlarm (nviDewPointAlarm), the controller will be set to the Building Protection setpoints. The cooling sequence is deactivated.

Override control with the SNVT nviManOvrd

State	Value	Actuator
HVO_OFF	—	Override control inactive
HVO_POSITION	percent	Position in % (MIN...MAX)
HVO_FLOW_VALUE	flow	—
HVO_FLOW_PERCENT	percent	—
HVO_OPEN	—	Full open
HVO_CLOSE	—	Full closed
HVO_MINIMUM	—	Minimum position
HVO_MAXIMUM	—	Maximum position

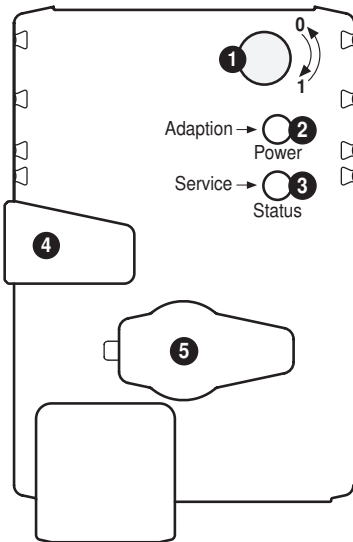
Note

The basic setting is «HVO_OFF». This value is loaded when the power supply is switched on.

Note

More detailed information on the functional profiles can be found on the website of LONMARK® (www.lonmark.org).

Operating controls and indicators



1 Direction of rotation switch

Switch over: Direction of rotation changes

2 Push-button and LED display green

Off: No power supply or malfunction

On: In operation

Press button: Triggers angle of rotation adaptation, followed by standard mode

3 Service button for commissioning at LONWORKS® and LED display yellow for LON status

Off: The actuator is linked to the LONWORKS® and ready for operation

On: No application software is loaded in the actuator

Flashing, interval 2 s: The actuator is ready for operation, but not linked to the LONWORKS® (unconfigured)

Other flashing codes: There is a malfunction in the actuator

Press button: Service Pin Message is sent to the LONWORKS®

4 Gear disengagement button

Press button: Gear disengages, motor stops, manual override possible

Release button: Gear engages, synchronisation starts, followed by standard mode

5 Service plug

For connecting parameterisation and service tools

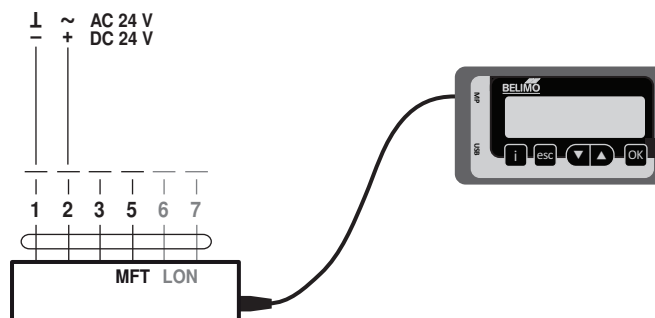
Service



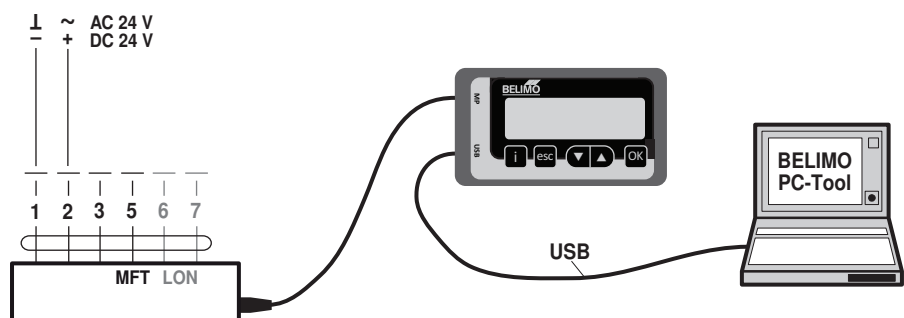
Notes

- The actuator can be parameterised by PC-Tool and ZTH EU via the service socket.

ZTH EU connection

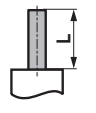
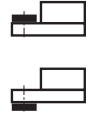




PC-Tool connection






Dimensions [mm]

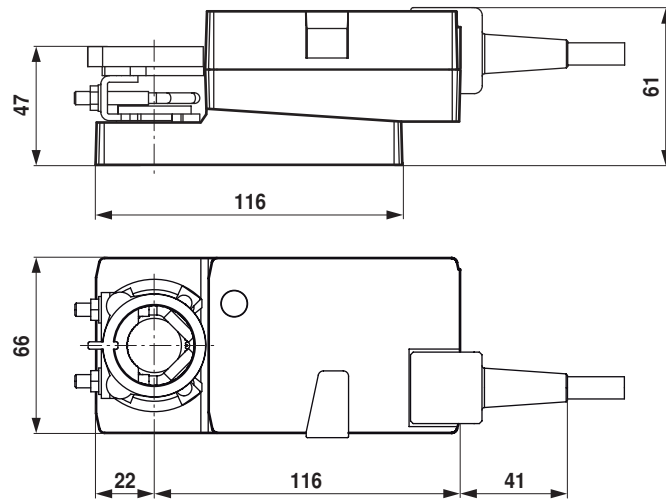
Spindle length

		Min. 37
		-

Clamping range

		
6...20	≥6	≤20

Dimensional drawings



Further documentation

- Applications with integrated temp. controller
- LON actuators with CO₂ control
- Actuator Plug-in description
- Sensor Plug-in description
- Controller Plug-in description
- Tool connections
- LonWorks® Glossary